



UNIVERSITY OF LISBON  
INTERDISCIPLINARY STUDIES  
ON SUSTAINABLE ENVIRONMENT AND SEAS



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Co-funded by the  
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# Unmanned Aerial Vehicles for Environmental Monitoring

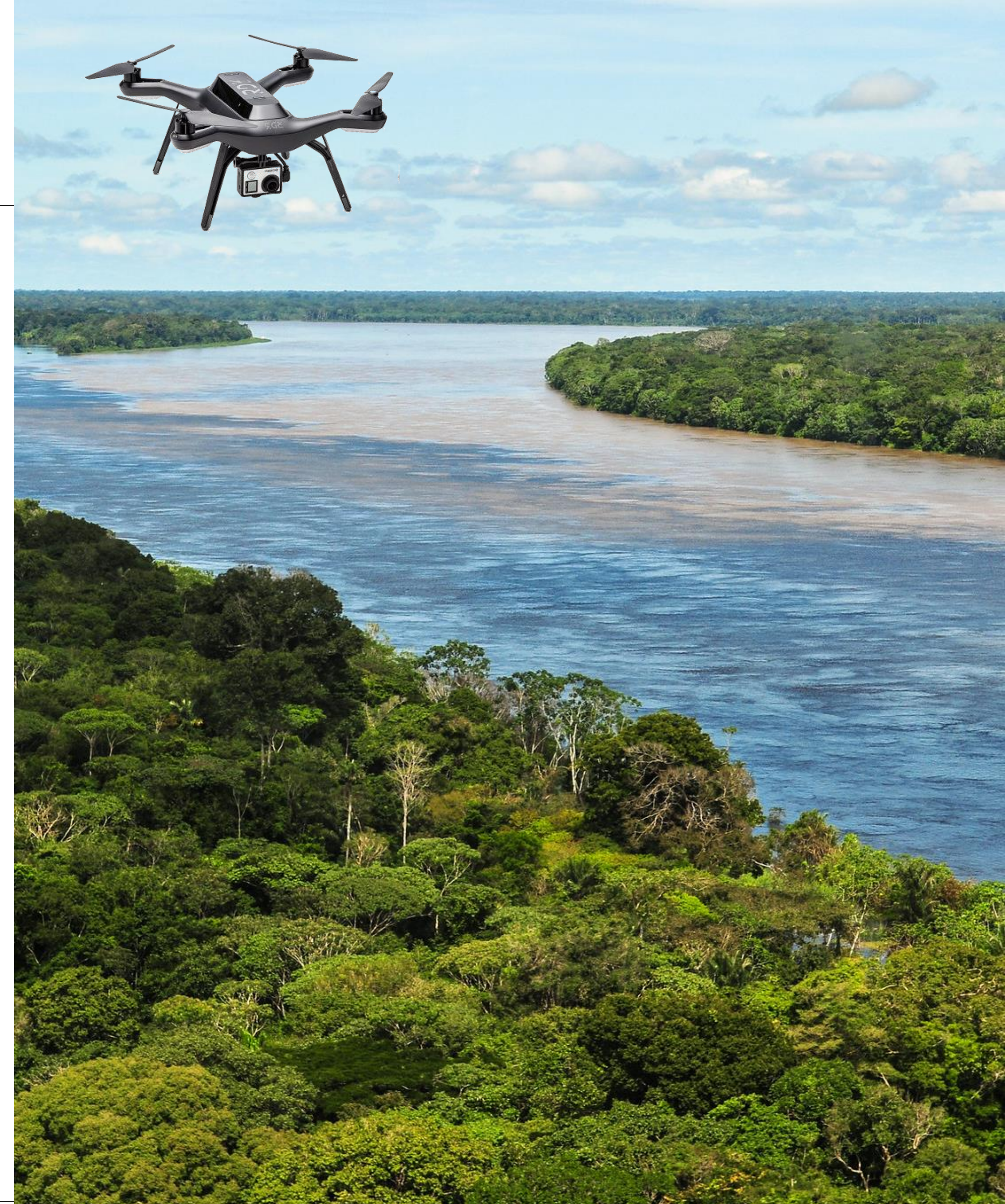
**Alexandra Moutinho**

Control, Automation and Industrial Informatics  
Mechanical Engineering Department  
Instituto Superior Técnico, Universidade de Lisboa



# Module contents

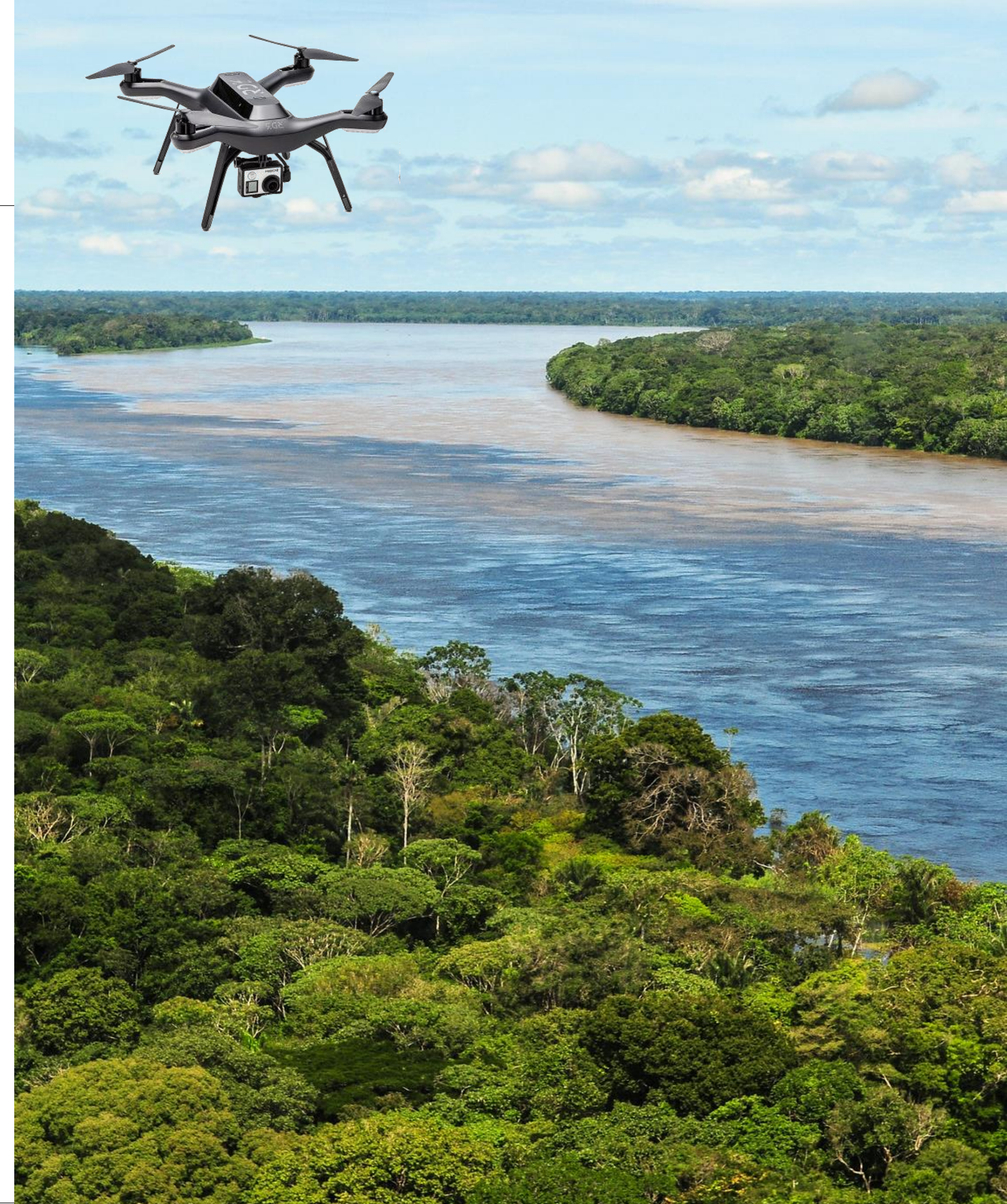
1. Introduction to Unmanned Aerial Systems
2. UAVs payload: sensors for environmental monitoring
3. UAVs operation
4. Examples of application of UAVs for environmental monitoring



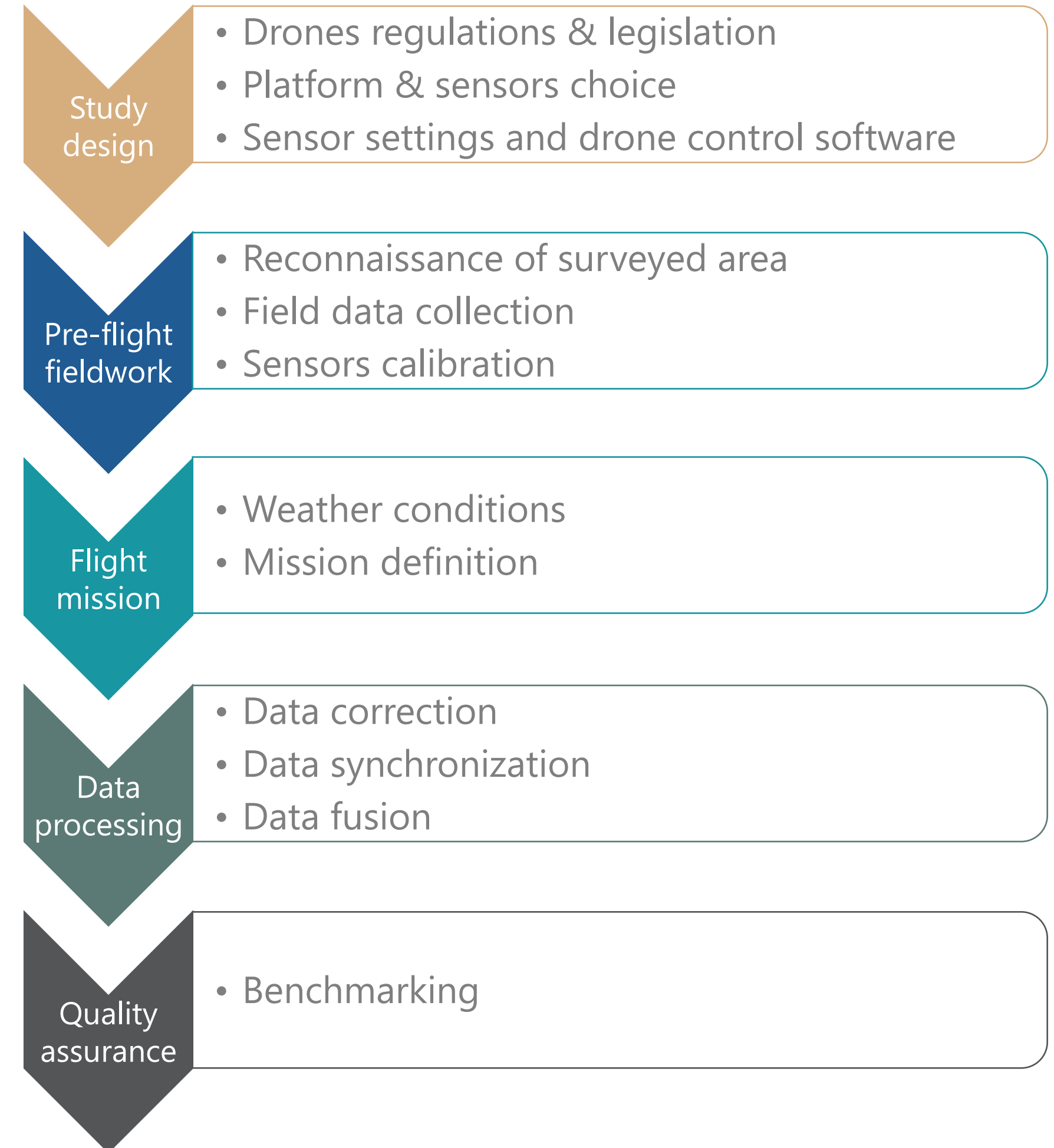
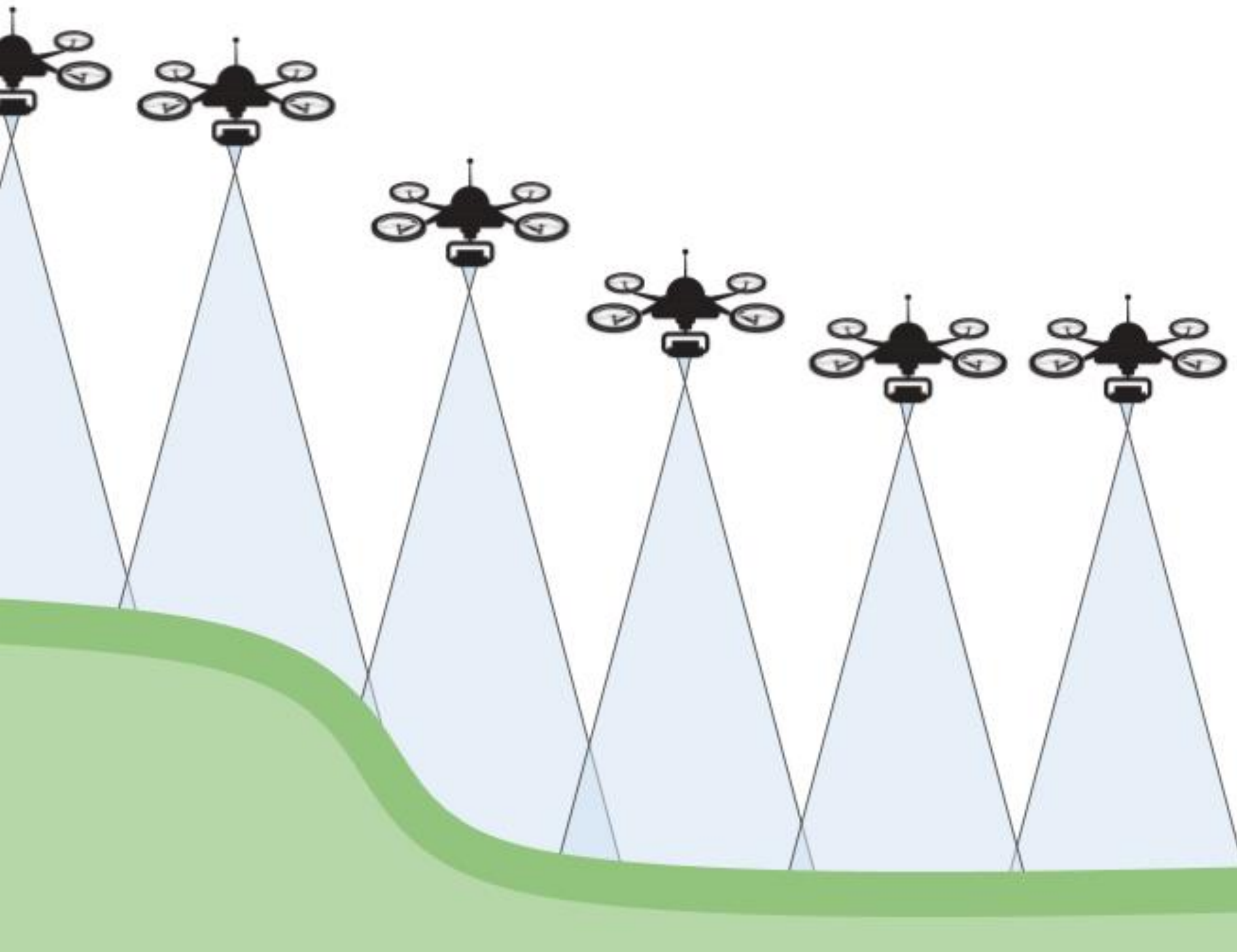


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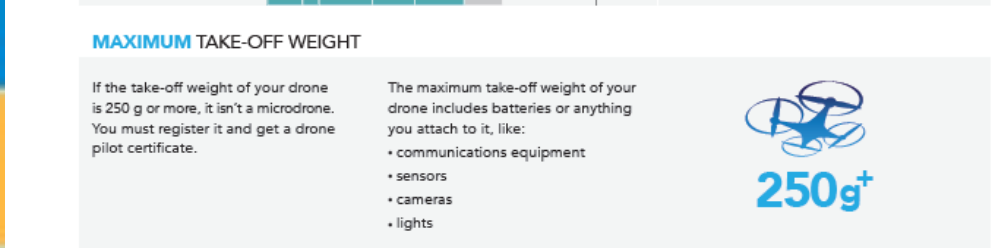
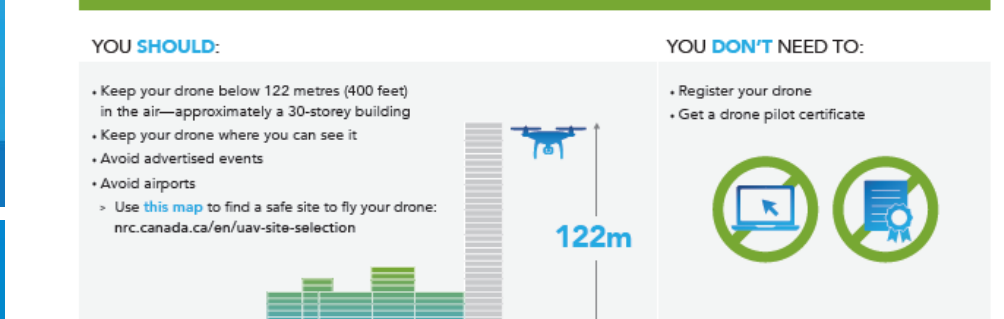
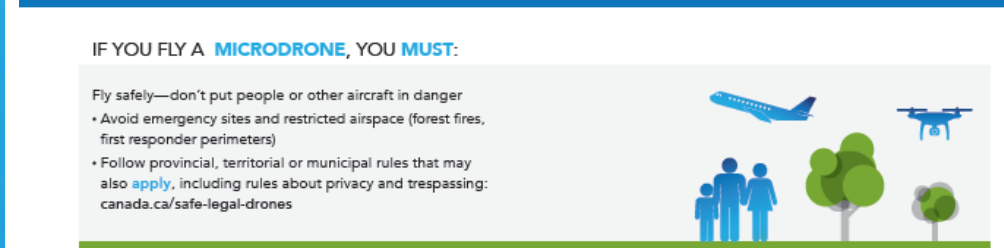
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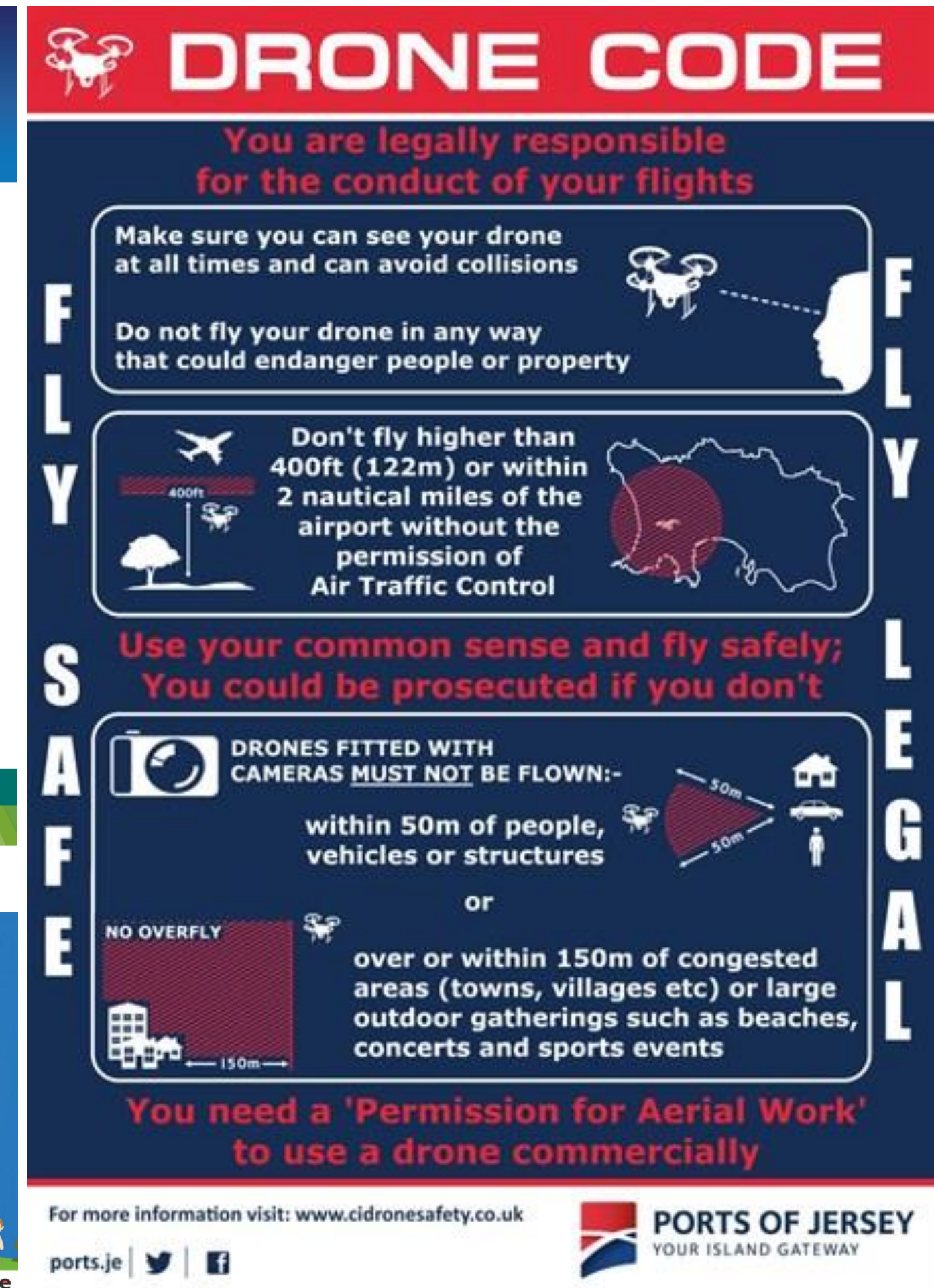
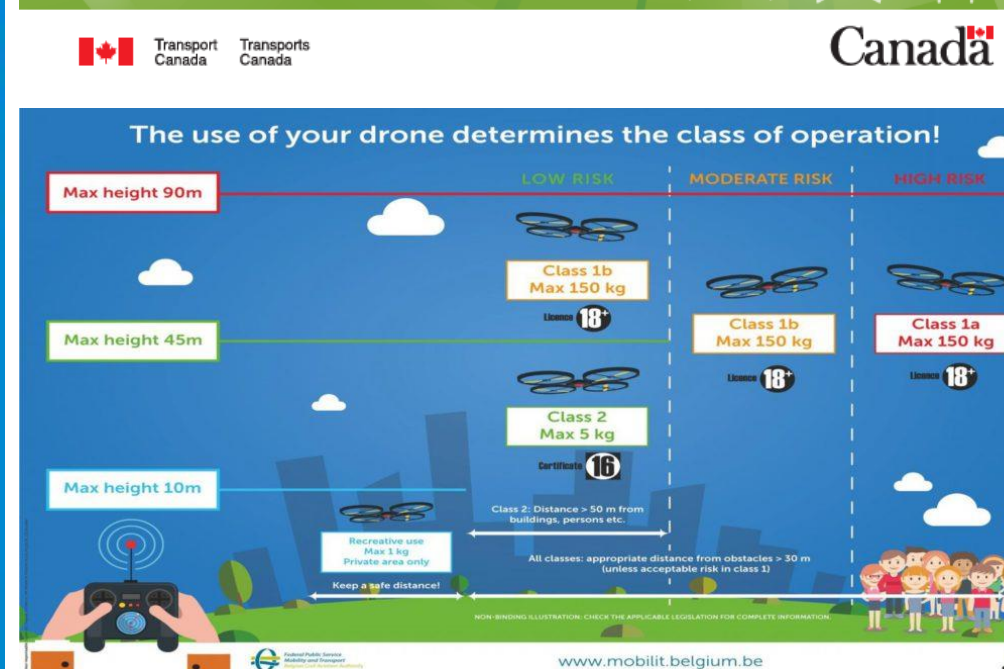




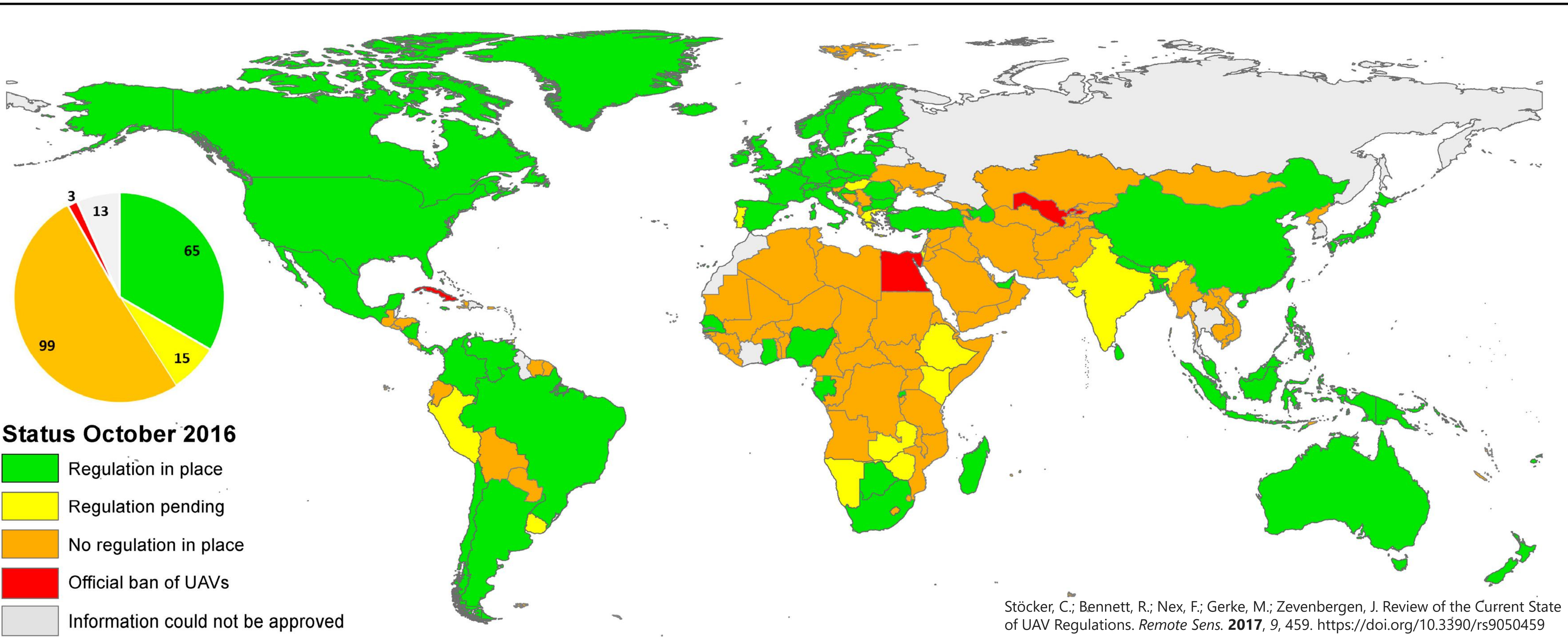




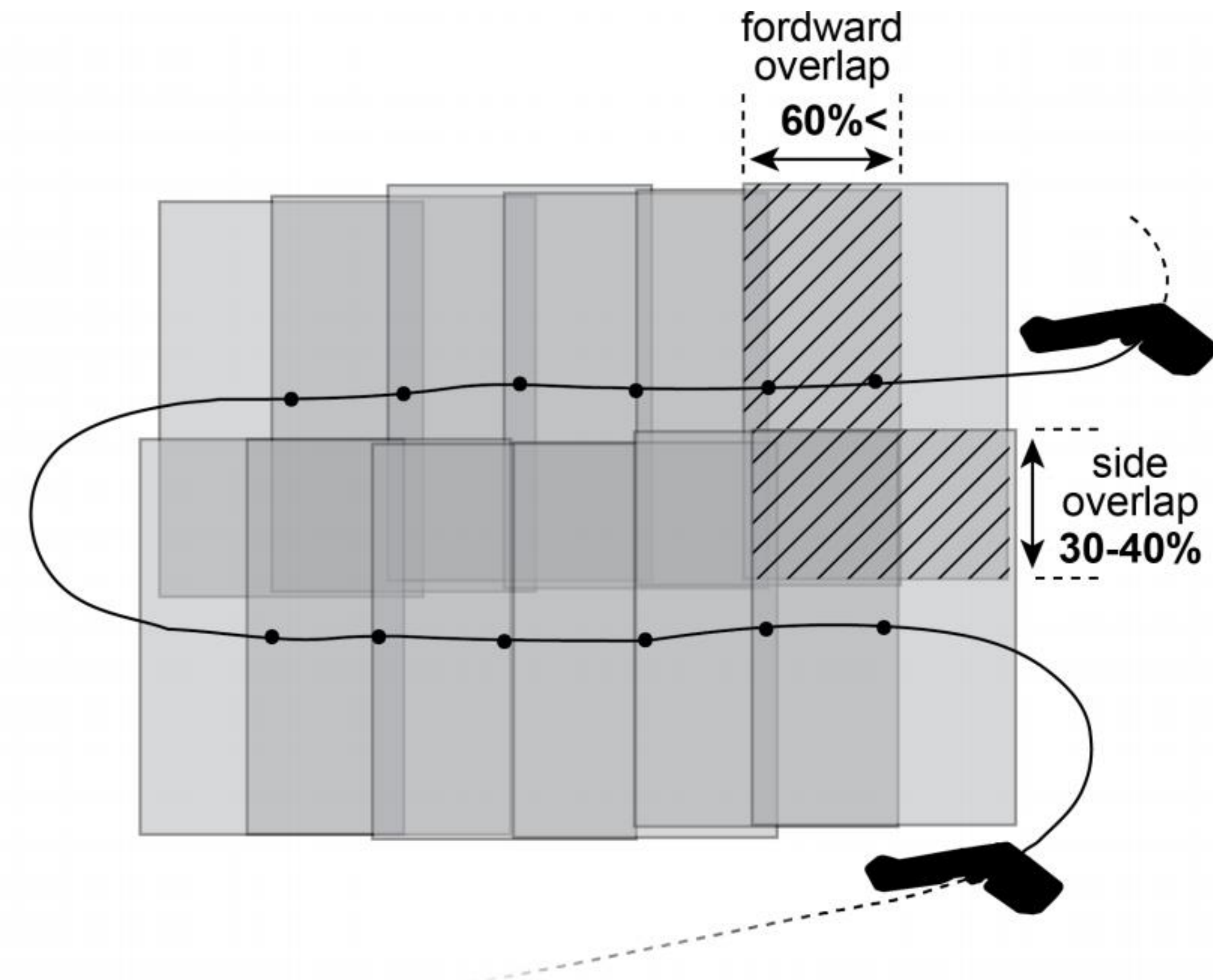
IF YOU BREAK THE RULES, YOU COULD BE FINED \$1,000 (FOR AN INDIVIDUAL) OR \$5,000 (FOR A CORPORATION)





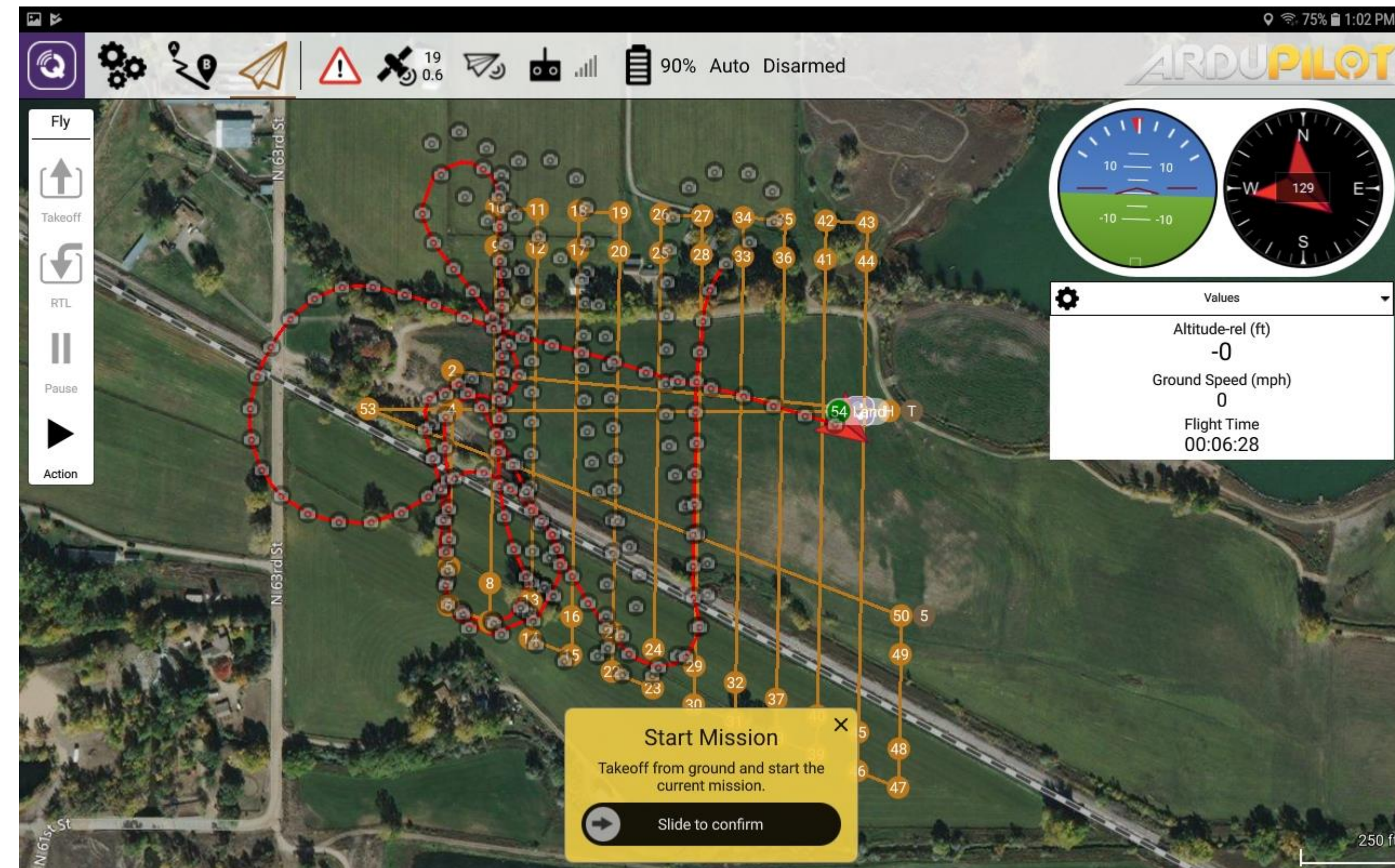
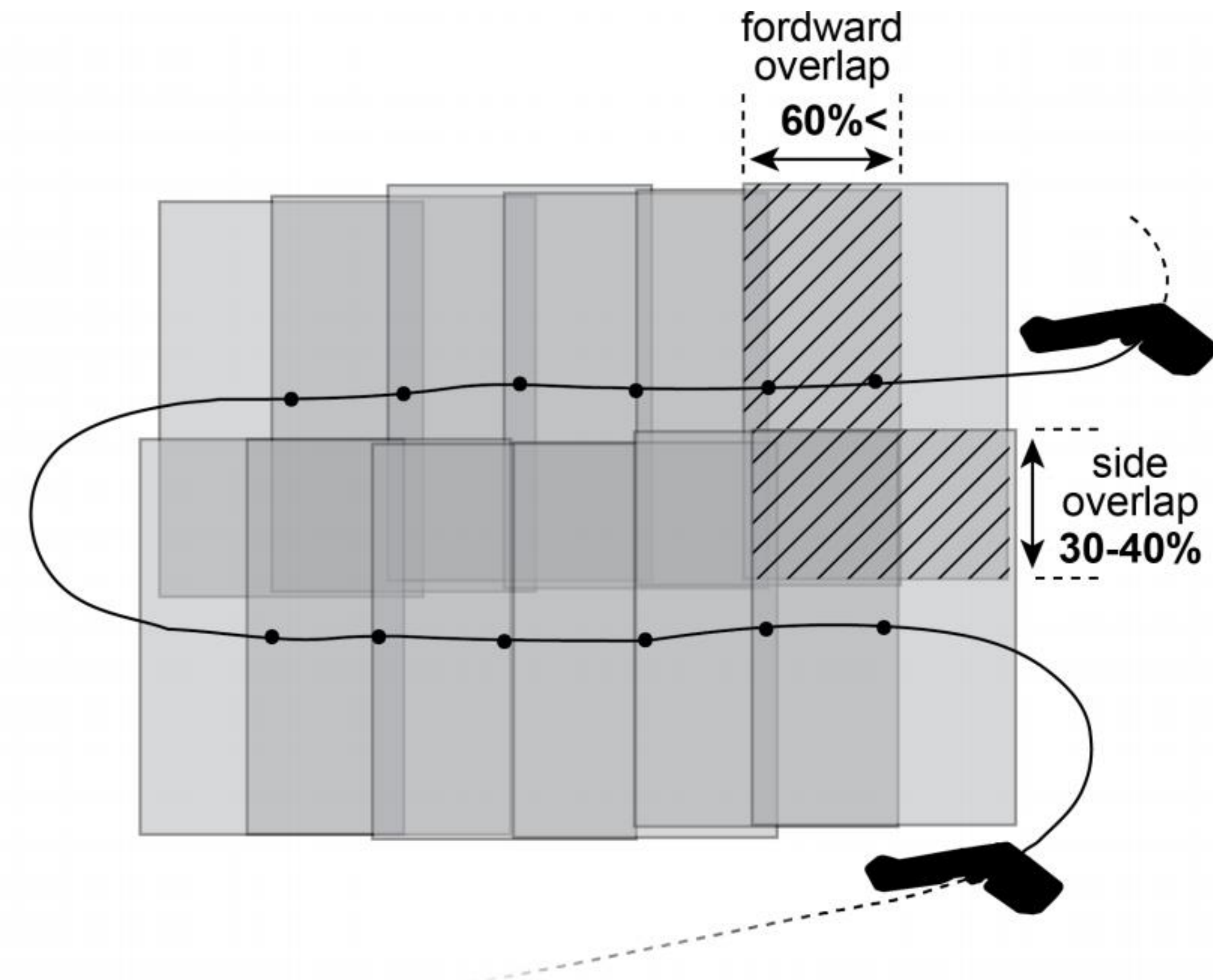






Goran Tmušić, Salvatore Manfreda, Helge Aasen, et al., Current Practices in UAS-based Environmental Monitoring, Remote Sensing, 2020, 12, 1001; doi:10.3390/rs12061001





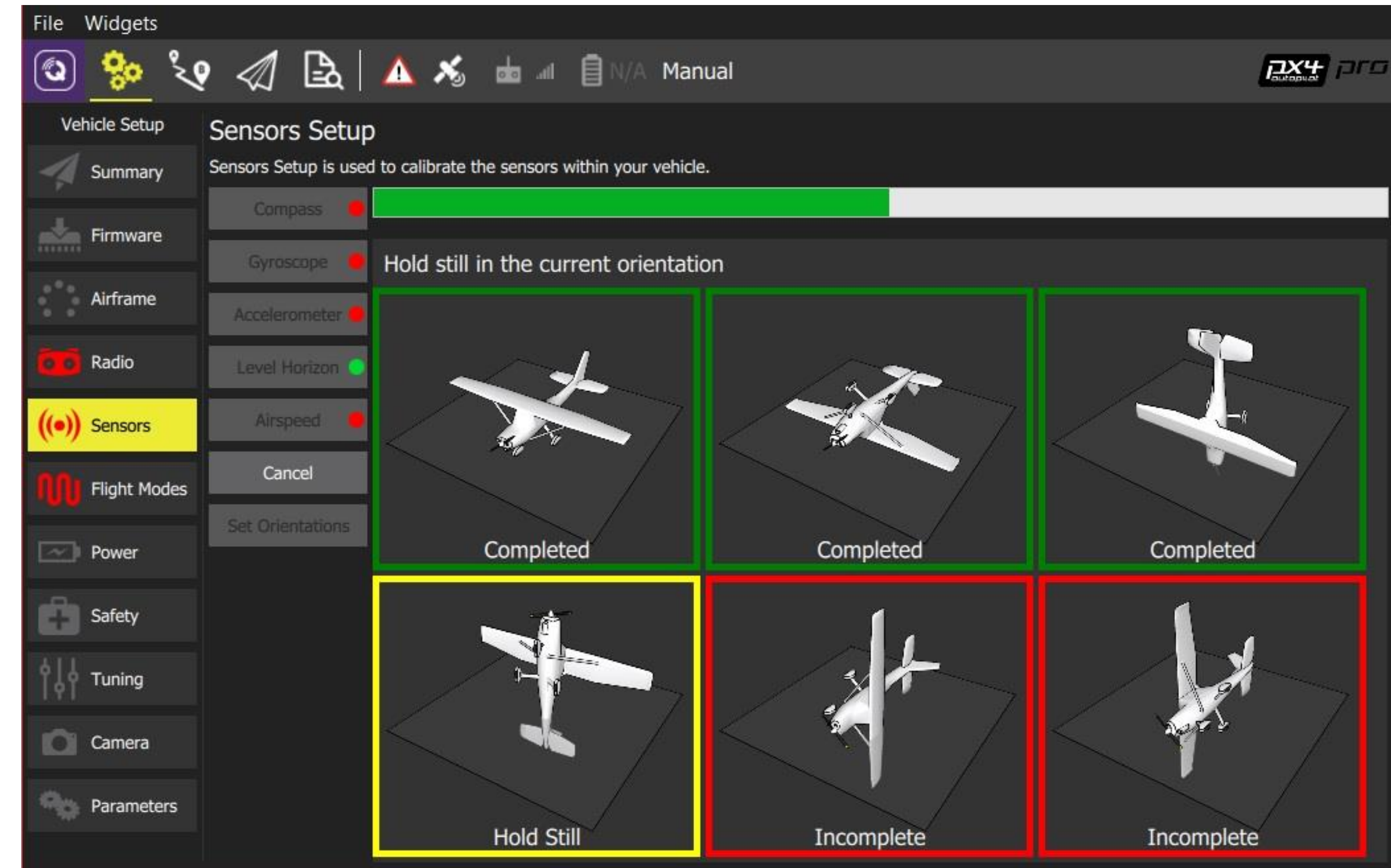
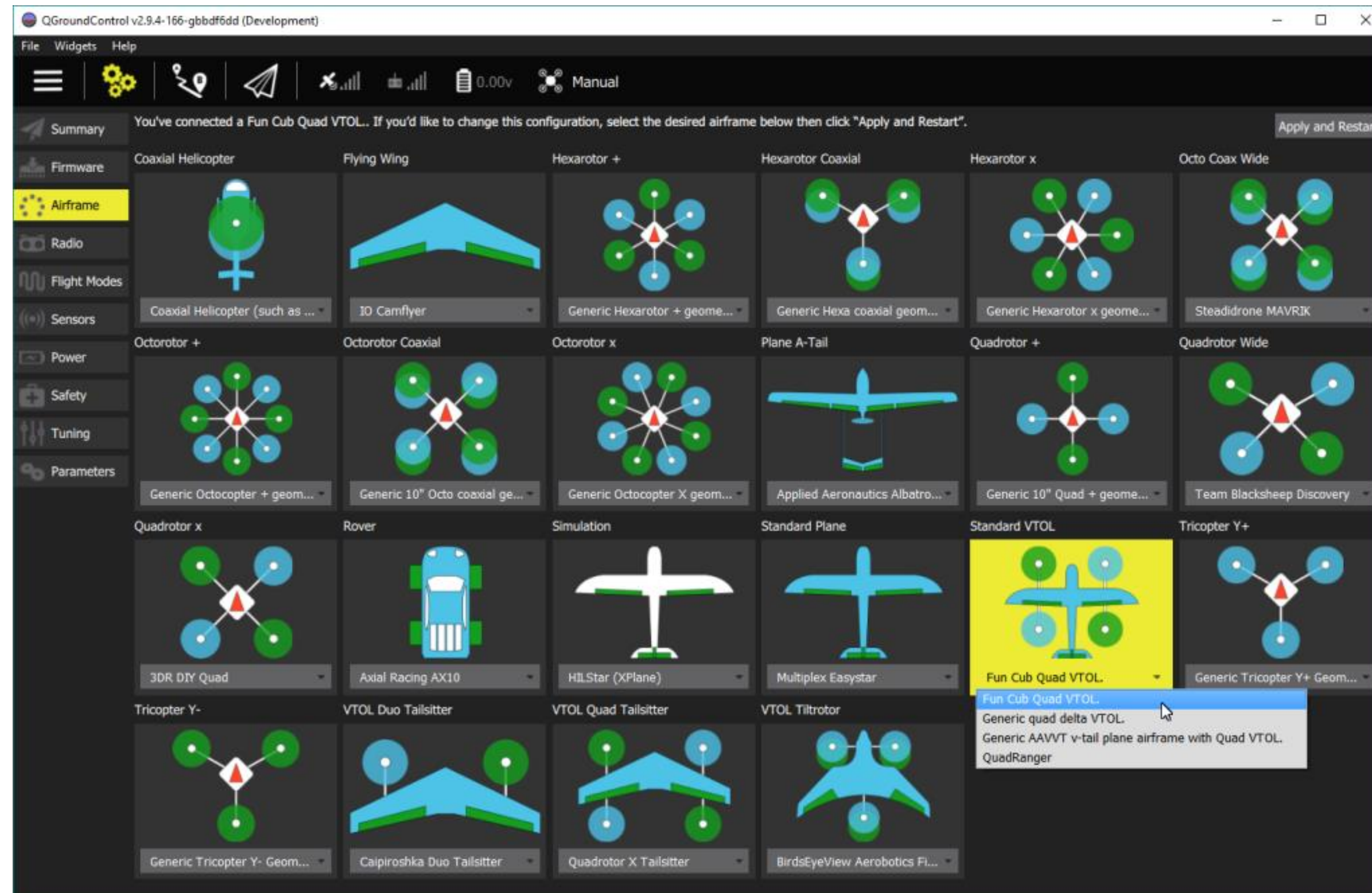
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	Name	Software (SW) Options	Operating System	Home Page	Type of License
Flight planning app	Pix4Dcapture	Planar flights; Double gridded flights; Circular Flights.	Android/iOS/Windows	<a href="http://pix4d.com/product/pix4dcapture">http://pix4d.com/product/pix4dcapture</a>	Free to use
	DJI GS Pro	3D mapping	iOS	<a href="http://dji.com/ground-station-pro">http://dji.com/ground-station-pro</a>	Free to use
	Precision flight free	Resume interrupted flights.	Android	<a href="http://precisionhawk.com/precisionflight">http://precisionhawk.com/precisionflight</a>	Free to use
	DroneDeploy	Planar flights; Cloud-based orthomosaics.	Android/iOS	<a href="https://www.dronedeploy.com/">https://www.dronedeploy.com/</a>	Free to use
	Litchi	Art computer vision algorithms; the gimbal and the drone's yaw axis.	Android/iOS	<a href="https://flylitchi.com/">https://flylitchi.com/</a>	Proprietary SW
	Phenofly Planning tool	Photographic properties, GCP placement, Viewing angle estimation	JavaScript browser	<a href="http://www.phenofly.net/PhenoFlyPlanningTool">http://www.phenofly.net/PhenoFlyPlanningTool</a>	Free to use & modify
Ground station software	MAVProxy	Loadable modules.	Portable Operating System (POSIX)	<a href="https://ardupilot.github.io/MAVProxy/html/index.html">https://ardupilot.github.io/MAVProxy/html/index.html</a>	Free to use
	Mission Planner	Hardware-in-the-loop UAV simulator.	Windows	<a href="http://ardupilot.org/planner">http://ardupilot.org/planner</a>	Free to use
	APM Planner 2/Mission Planner	Live data; Initiate commands in flight.	Linux/OS X/Windows	<a href="http://ardupilot.org/planner">http://ardupilot.org/planner</a>	Free to use
	QGroundControl GCS	Multiple vehicles.	Android/iOS/Linux/OS X/Windows	<a href="http://www.qgroundcontrol.org/">http://www.qgroundcontrol.org/</a>	Free to use & modify
	UgCS	Photogrammetry; Custom elevation data import; battery change option.	OS X/Linux/Windows	<a href="https://www.ugcs.com/">https://www.ugcs.com/</a>	Proprietary SW
	mdCOCKPIT	Real-time telemetric data; Flight analytics Module.	Android	<a href="http://microdrones.com/en/mdaircraft/software/mdcockpit">http://microdrones.com/en/mdaircraft/software/mdcockpit</a>	Proprietary SW
	UAV Toolbox	Telemetry data conversion.	Android	<a href="http://uavtoolbox.com/">http://uavtoolbox.com/</a>	Proprietary SW
	eMotion 3	Supports both fixed-wing and multirotor operations; Full 3D environment for flight management.	Windows	<a href="http://sensefly.com/software/emotion-3.html">http://sensefly.com/software/emotion-3.html</a>	Proprietary SW

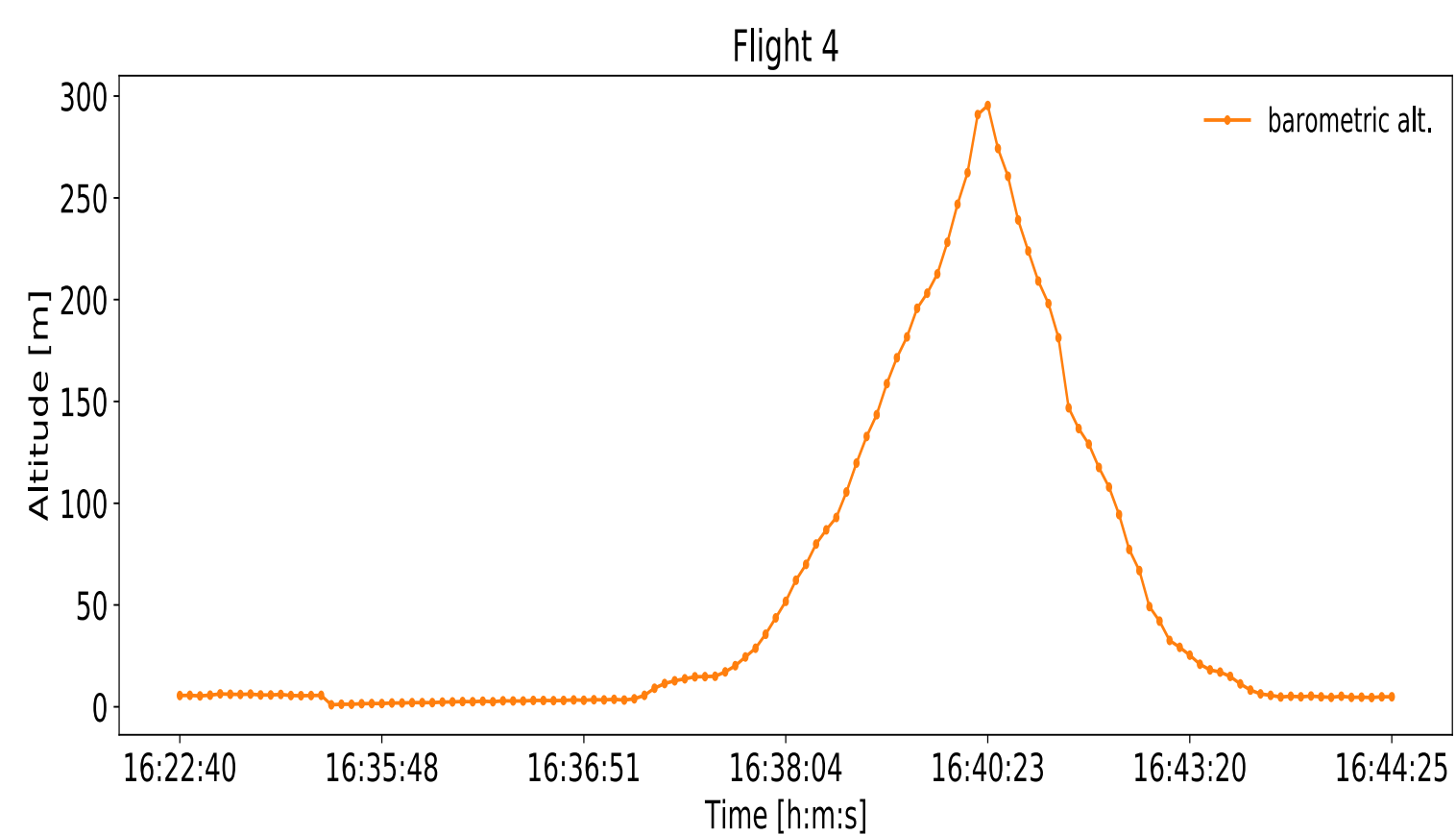
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# Data processing, synchronization, and fusion





An underwater scene with a sea turtle swimming towards the left. The water is filled with various types of plastic pollution, including bags, bottles, and debris. Several fish are swimming around the turtle. The overall color palette is blue and teal.

# Ulisses

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